

# Atomic Routing Games on Maximum Congestion

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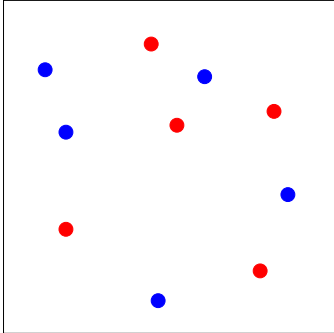


# Outline

- **Motivation and Problem Set Up;**
- **Related Work and Our Contributions;**
- **Proof Sketches;**
- **Wrap Up.**

# Routing

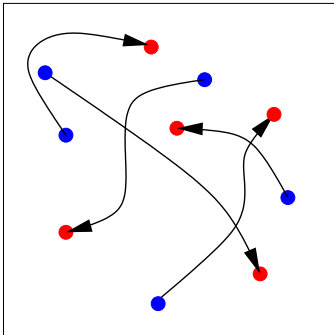
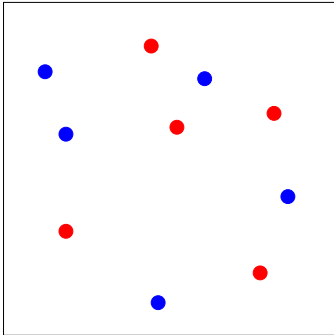
**Routing:** construct “good” paths given sources and destinations.



- Communication Networks – eg. **Internet**.
- Ad-hoc Networks – eg. sensor networks.
- Parallel Architectures – eg. Mesh.
- . . . .

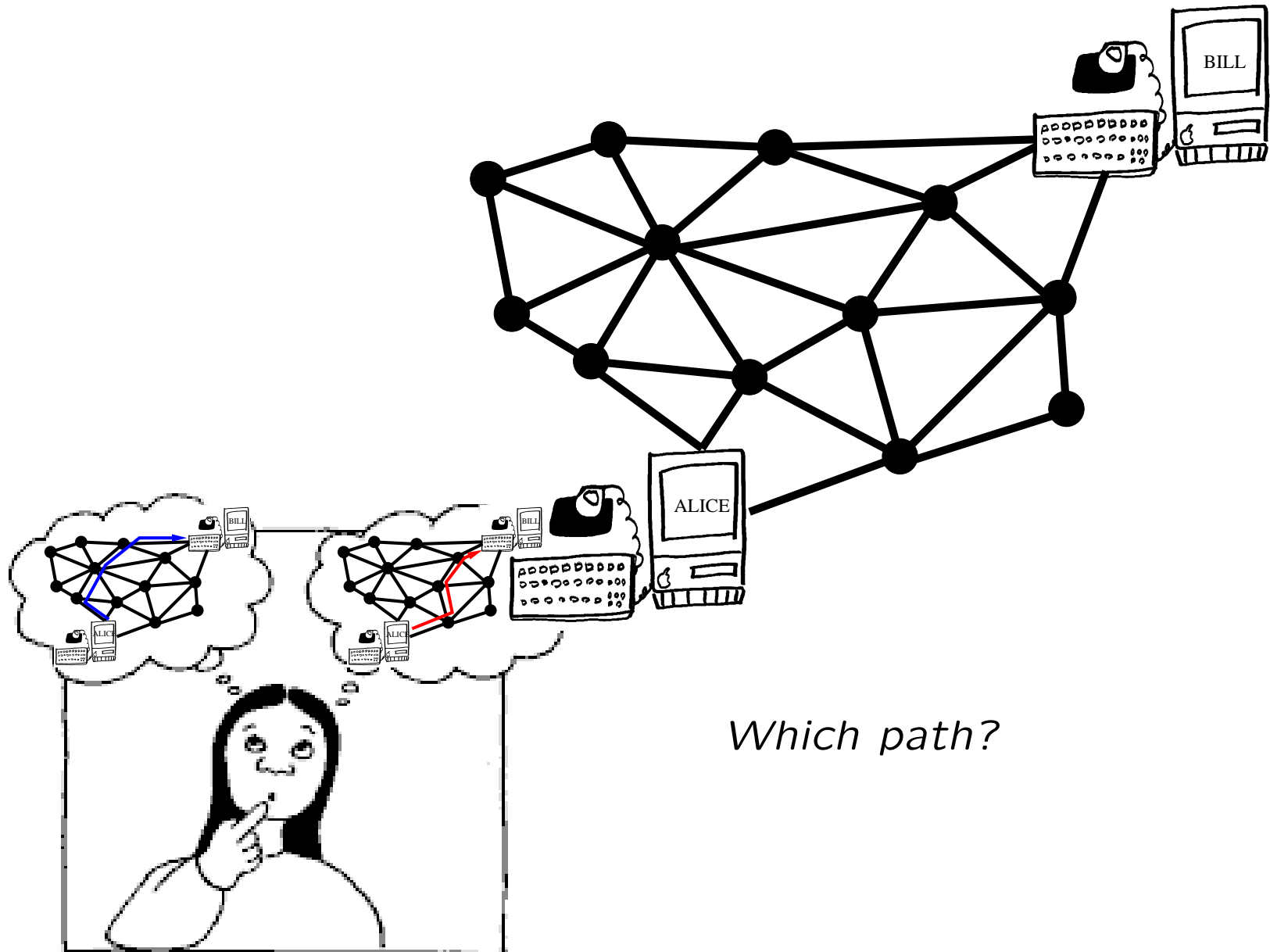
# Routing

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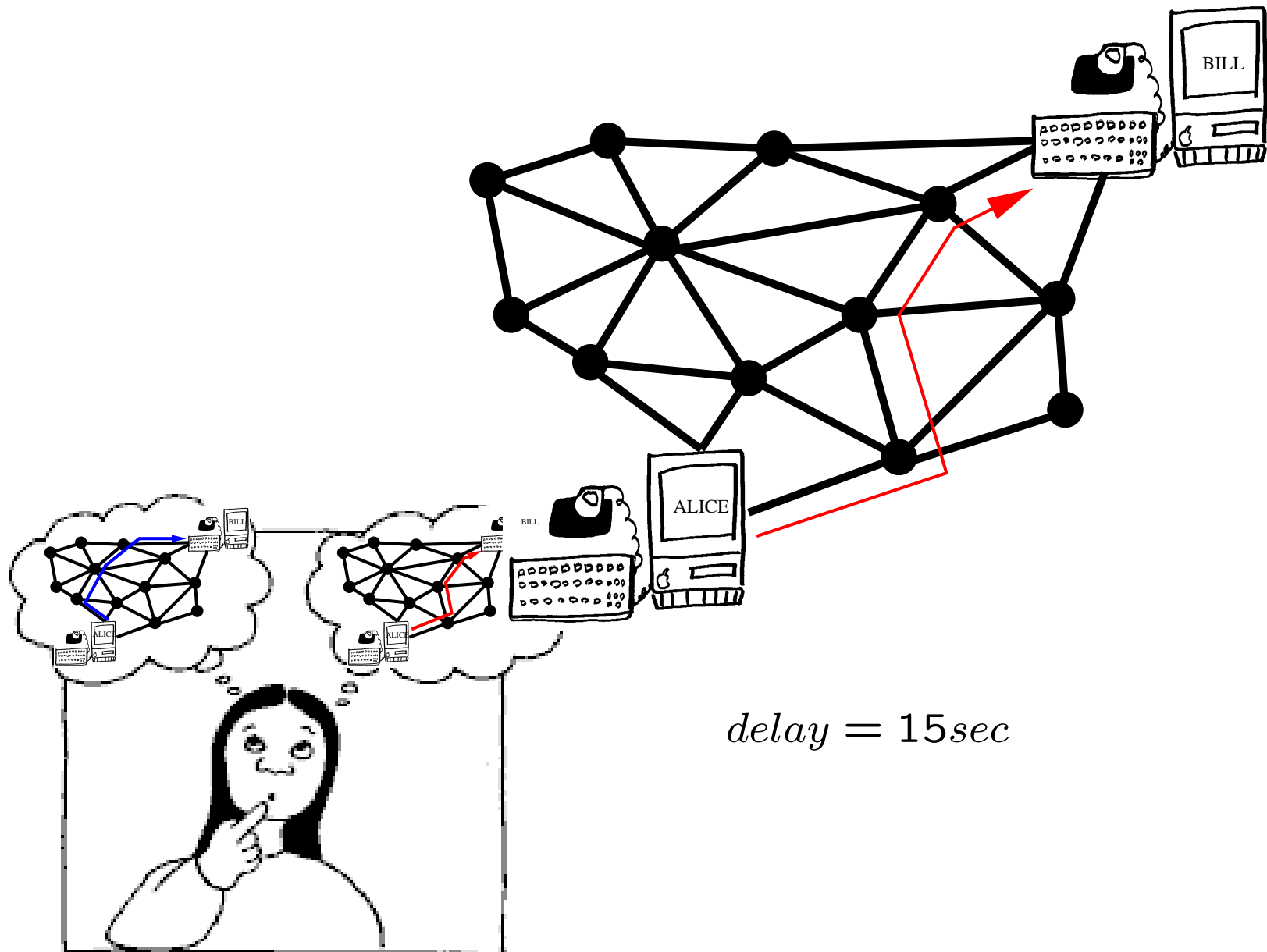


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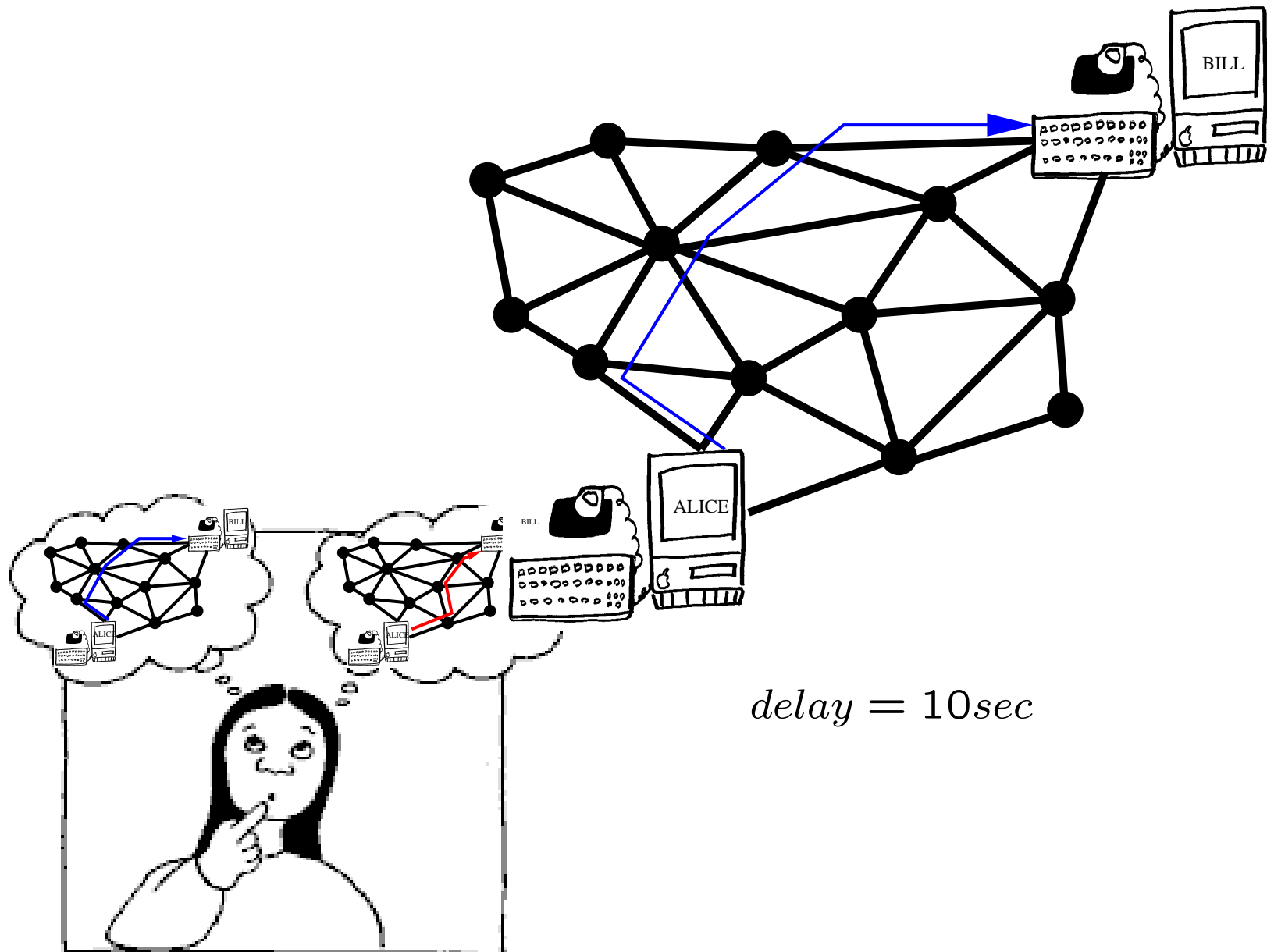
# Motivation



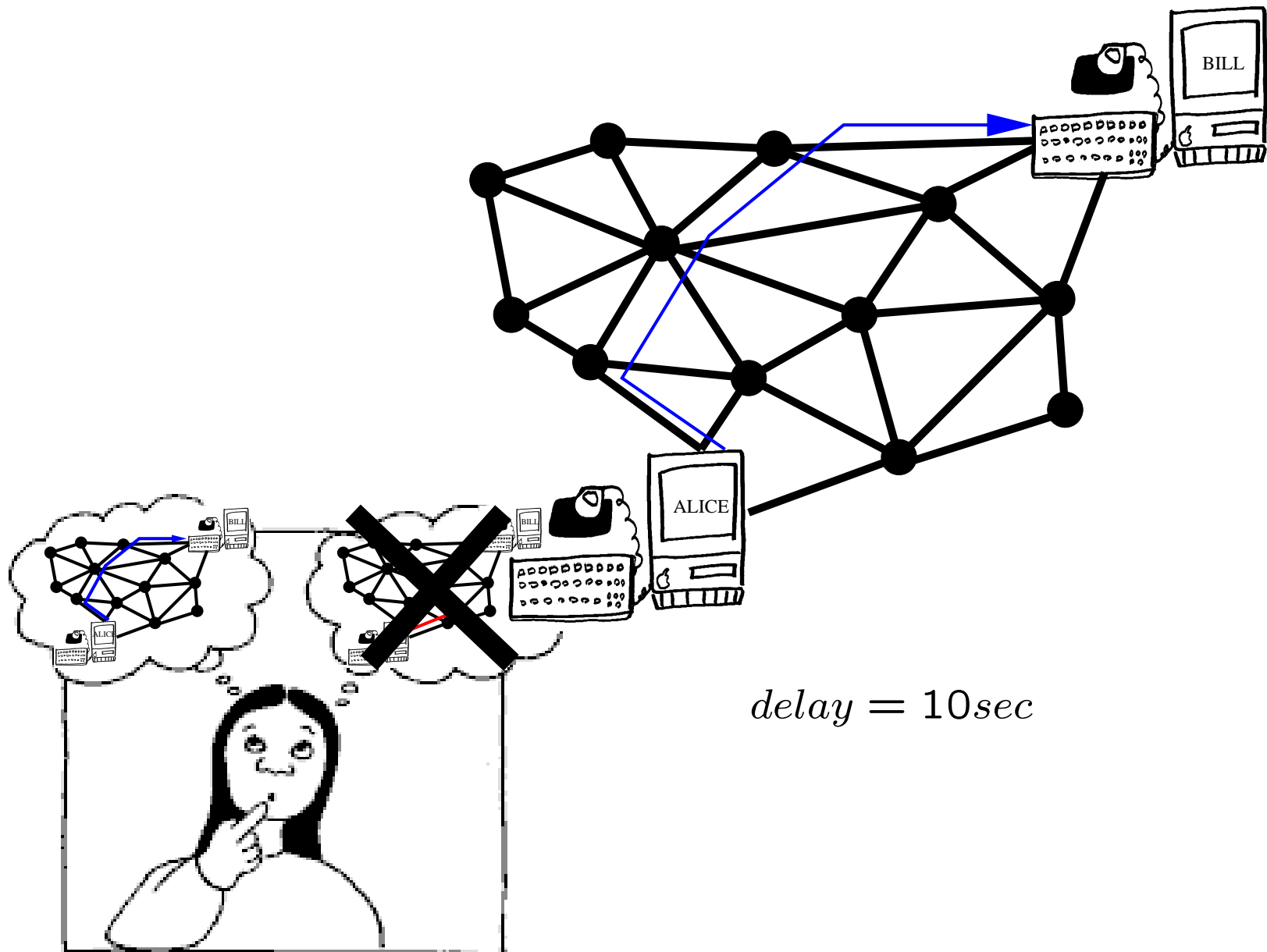
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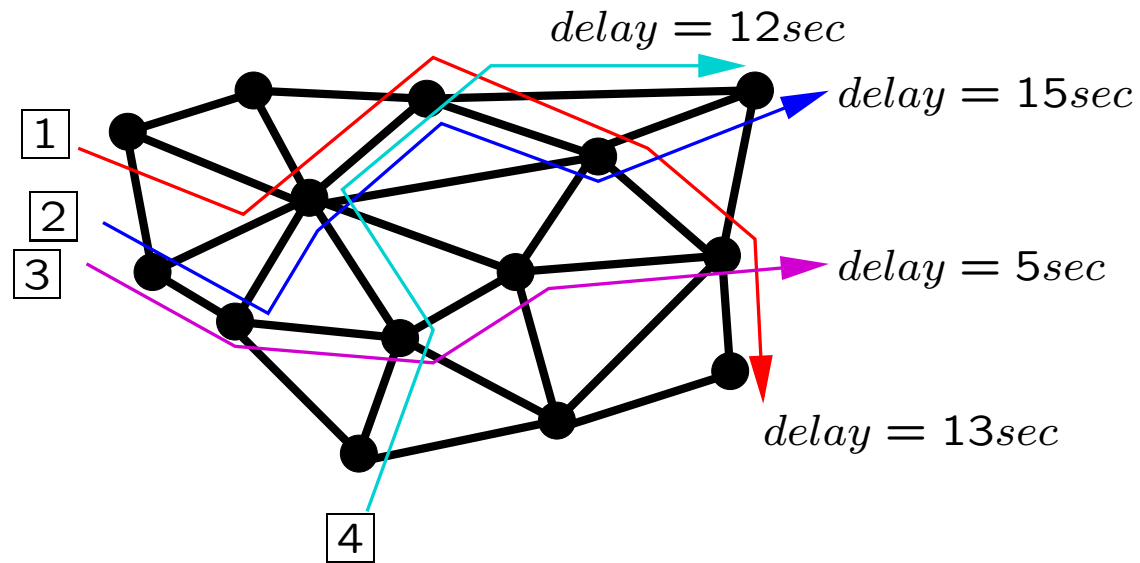


# Routing Games

- **Selfish players:** everyone will change paths to minimize their delay.  
**Best Response Dynamic**
- **Nash-Routing:** no-one wishes to change her path selection, given what everyone else is doing.

**We study properties of this process.**

# Routing Games



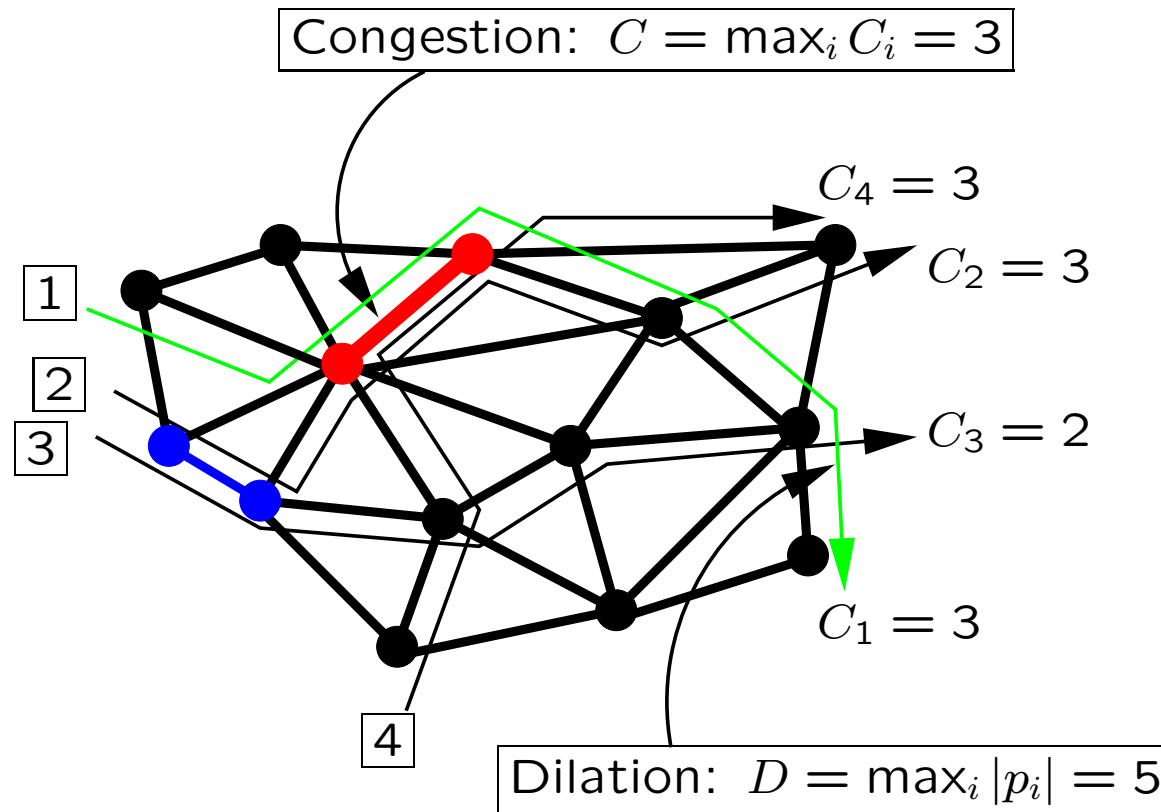
**Player cost**  $pc_i$ : delay of player  $i$ 's packet.

**Social cost**  $SC$ : maximum delay over all players.

$$SC = 15sec$$

**Players minimize their player cost selfishly**  
**Ideally, social cost should be minimized.**

# Quantifying Delay



$C_i$  is the largest congestion on path  $p_i$ .

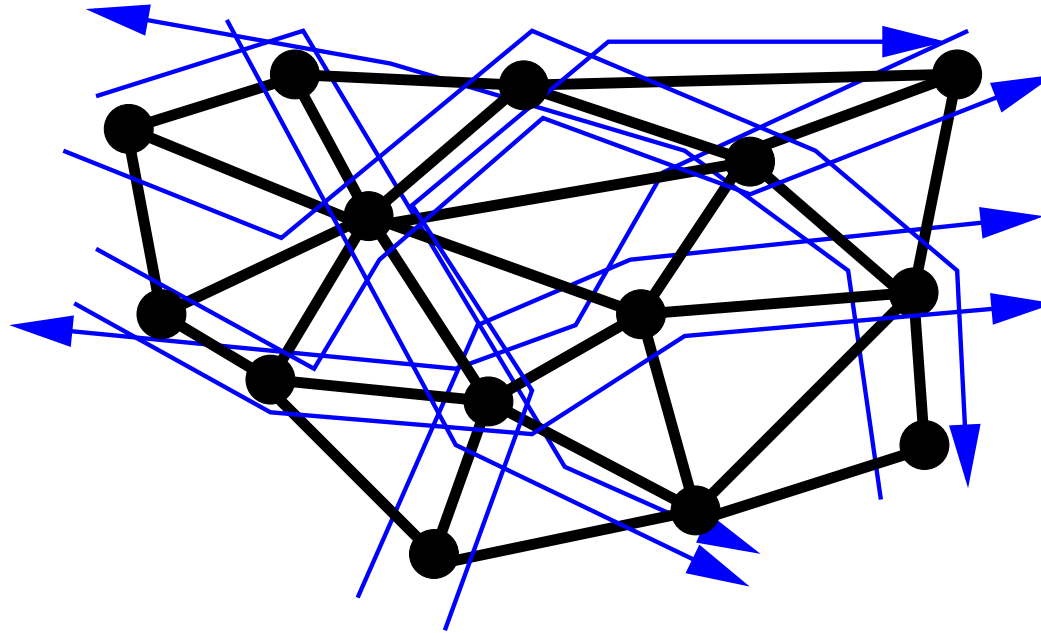
**Social Cost:**  $\max_i \text{delay}_i = O(C + D)$

**Player Cost:**  $\text{delay}_i = \tilde{O}(C_i + |p_i|)$

[LMR95]

[BS95]

# Congested Networks



$$C \gg D, C_i \gg |p_i|$$

Social Cost:  $\max_i \text{delay}_i = O(C)$

Player Cost:  $\text{delay}_i = \tilde{O}(C_i)$

# Formal Setup

**Routing (Congestion) Game:**  $(\mathbf{N}, G, \{\mathcal{P}_i\}_{i \in \mathbf{N}})$ .

$\mathbf{N} = \{1, 2, \dots, N\}$  – players, i.e. (*source, dest*) pairs;

$G = (V, E)$  – network;

$\mathcal{P}_i$  – strategy sets (*edge-simple* paths).

**Routing:**  $\mathbf{p} = [p_1, p_2, \dots, p_N]$  – *pure strategy profile*.

**Congestion:**  $C_e(\mathbf{p}) = \#$  paths using edge  $e$ .

**Path Congestion:**  $C_i(\mathbf{p}) = \max_{e \in p_i} C_e(\mathbf{p})$ ;

**Network Congestion:**  $C(\mathbf{p}) = \max_i C_i(\mathbf{p})$ ;

**Social Cost:**  $SC(\mathbf{p}) = C(\mathbf{p})$  (Network Congestion).

**Player Cost:**  $pc_i(\mathbf{p}) = C_i(\mathbf{p})$  (Player's Path Congestion).

**Nash-routing  $\mathbf{p}$ :**  $pc_i(\mathbf{p}) \leq pc_i(\mathbf{p}')$  ( $\mathbf{p}'$  differs from  $\mathbf{p}$  only in  $p_i$ ).

(No one can unilaterally improve her situation in a Nash-routing.)

# Quality of Nash-Routings

$$\text{Price of Stability } PoS = \inf_{\mathbf{p} \in \mathbf{P}} \frac{SC(\mathbf{p})}{SC^*},$$

$$\text{Price of Anarchy } PoA = \sup_{\mathbf{p} \in \mathbf{P}} \frac{SC(\mathbf{p})}{SC^*}.$$

$PoS$ : minimum price for stability. (best possible selfish outcome)

$PoA$ : maximum price for stability. (worst possible selfish outcome)

Ideal:  $PoS = PoA = 1$ .

# Related Work

	Atomic Flow	Splittable Flow
Pure	█, █, [BM06]	█
Mixed	█	█, █

	Max $SC$	Sum $SC$	Other $SC$	
Max $pc$	[BM06]	—	—	█
Sum $pc$	█, █	█, █	█	█

- █: specific network or strategy sets (eg. parallel links or singleton sets).
- █: existence or convergence to equilibrium (do not look at quality ( $SC$ )).

Note: sum  $SC$  is relevant when network resources, not max. player delay is important.

# Our Contribution – $PoS$

Routing games with max. player/social costs on general networks.

## Theorem 1

(i)  $PoS = 1$ ;

(ii) All best response dynamics converge to a Nash-routing

$$SC(\mathbf{p}_{final}) \leq SC(\mathbf{p}_{start}).$$

- There exist good Nash-routing.
- Starting at any good routing, selfish players can only improve!  
Good oblivious starting routings: [MMVW97], [R02], [BMX05].

# Our Contribution – $PoA$

Routing games with max. player/social costs on general networks.

**Theorem 2**  $PoA < 2(\ell + \log n)$ .

$\ell$  upper bounds path lengths in the strategy sets.

$\ell$  can be small (eg. Hypercubes).

**Theorem 3**  $\kappa_e - 1 \leq PoA \leq c(\kappa_e^2 + \log^2 n)$ .

$\kappa_e(G)$  is the length of the longest cycle.

$PoA$  is bounded by topological properties of the network.

# Proof Sketch: $POS = 1$

Establish a total order  $\leq_c, <_c$  among routings with:

**Lemma 1** There exists a minimum routing  $\mathbf{p}^*$ . [Compactness of routings.]

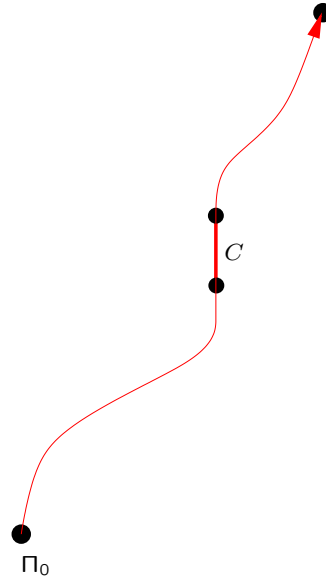
**Lemma 2**  $SC(\mathbf{p}) \leq SC(\mathbf{p}')$  iff  $\mathbf{p} \leq_c \mathbf{p}'$ .

**Lemma 3** If  $\mathbf{p} \rightarrow \mathbf{p}'$  in a selfish move, then  $\mathbf{p}' <_c \mathbf{p} \implies SC(\mathbf{p}') < SC(\mathbf{p})$ .

**Corollary** Minimum routings  $\mathbf{p}^*$  are a Nash-routings. Best response dynamics converge to better Nash-routing.

(Note: cf. potential function methods.)

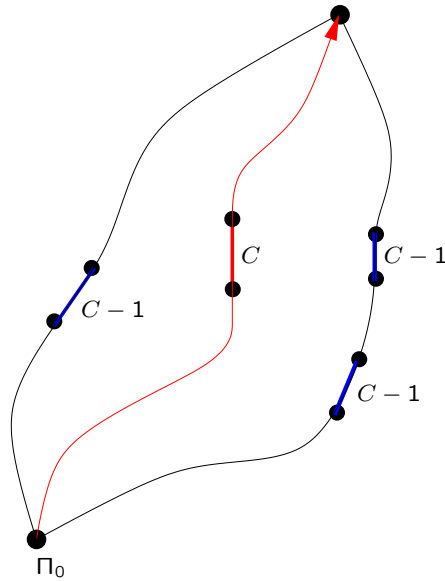
# Proof Sketch: $PoA \leq 2(\ell + \log n)$



$E_0$ : Edges of congestion  $C$ .

$\Pi_0$ : Players using edges in  $E_0$ .

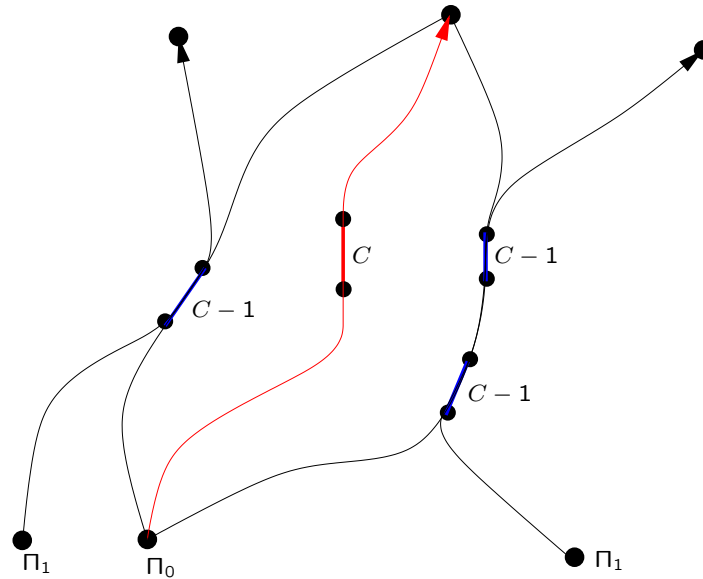
# Proof Sketch: $PoA \leq 2(\ell + \log n)$



Alternative paths for players in  $\Pi_0$  must all have at least one edge with congestion at least  $C - 1$ .

(  $E_0$ : Edges of congestion  $C$ .  
 $\Pi_0$ : Players using edges in  $E_0$ . )

# Proof Sketch: $PoA \leq 2(\ell + \log n)$



$E_1$ : All these edges of congestion  $\geq C - 1$ .

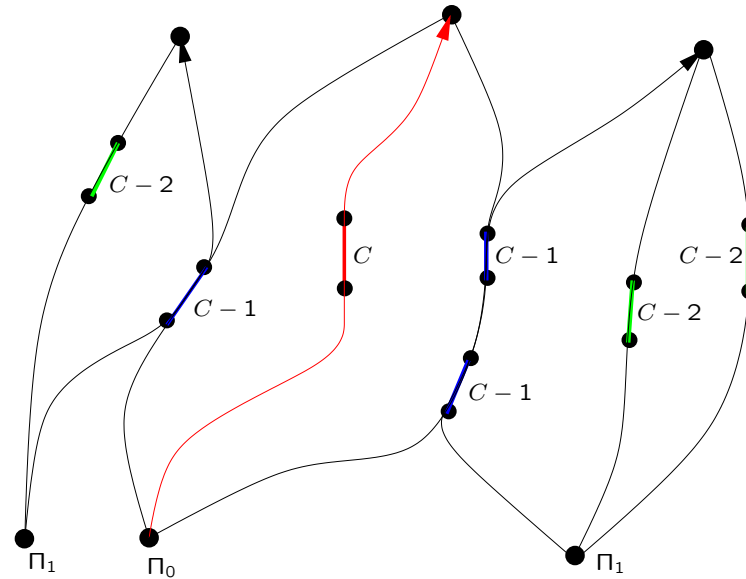
$\Pi_1$ : Players using edges in  $E_1$ .

if  $|E_1| \leq 2|E_0|$ , stop, else continue **Edge Expansion Process**

( $|E_0| = 1, |E_1| = 4$ )

( $E_1$  is formed from all possible paths of players in  $\Pi_0$ )

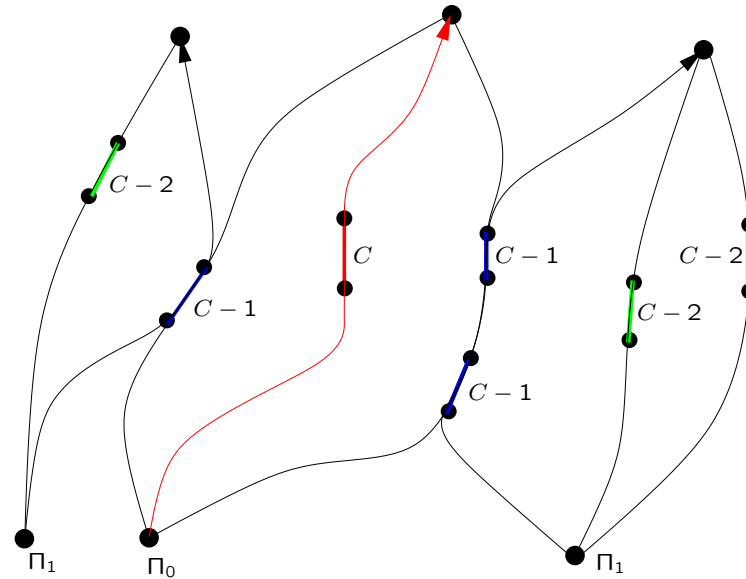
# Proof Sketch: $PoA \leq 2(\ell + \log n)$



Alternative paths for players in  $\Pi_1$  must all have at least one edge with congestion at least  $C - 2$ .

$\left( \begin{array}{l} E_1: \text{Edges of congestion at least } C - 1. \\ \Pi_1: \text{Players using edges in } E_1. \end{array} \right)$

# Proof Sketch: $PoA \leq 2(\ell + \log n)$



$E_2$ : All these edges of congestion  $\geq C - 2$ .

if  $|E_2| \leq 2|E_1|$ , stop.

$$(|E_1| = 4, |E_2| = 7)$$

( $E_2$  is formed from all possible paths of players in  $\Pi_1$ )

# Proof Sketch: $PoA \leq 2(\ell + \log n)$

$$E_0 \quad E_1 \quad \dots \quad E_{s-1} \quad E_s$$

$$\Pi_0 \quad \Pi_1 \quad \dots \quad \Pi_{s-1}$$

$$s \leq \log n$$

(Each step doubles the size of  $E_i$ .)

Max. # times  
edges used by  
packets in  $\Pi_{s-1}$

Min. # times edges in  
 $E_{s-1}$  used (only packets  
in  $\Pi_{s-1}$  use edges in  $E_{s-1}$ )

$$|\Pi_{s-1}| \cdot \ell \geq (C - (s - 1)) \cdot |E_{s-1}|$$

$$C_{opt} \geq \frac{|\Pi_{s-1}|}{|E_s|} \geq \frac{|\Pi_{s-1}|}{2|E_{s-1}|}$$

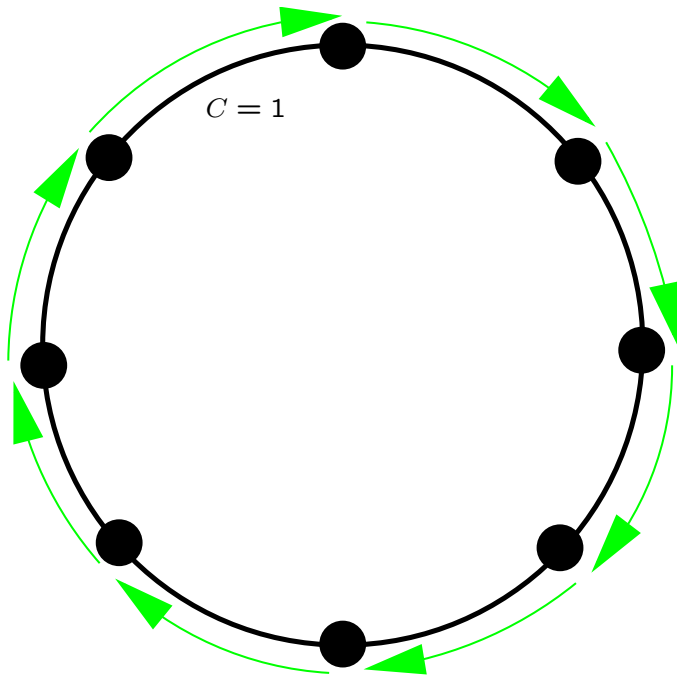
Optimal C

Every packet in  $\Pi_{s-1}$   
must use at least one  
edge in  $E_s$

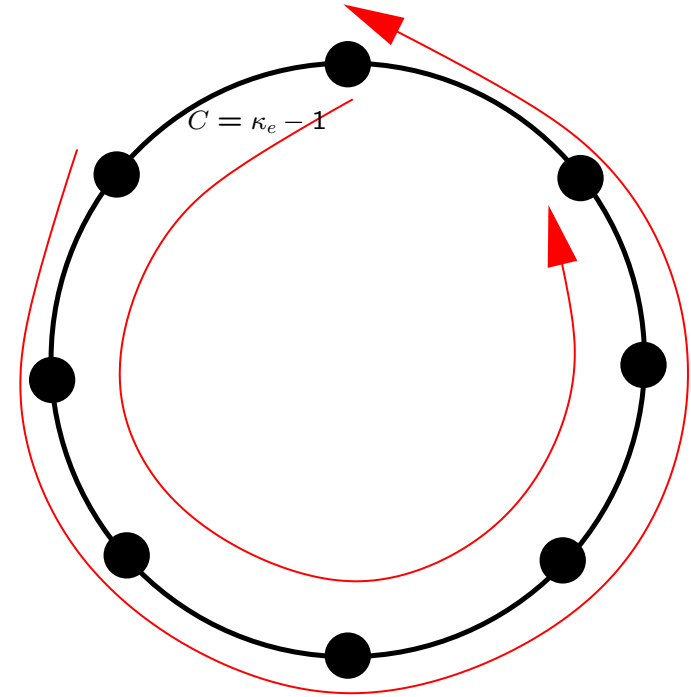
$|E_s| \leq 2|E_{s-1}|$

$$PoA = \frac{C}{C_{opt}} \leq 2\ell + s - 1.$$

# Proof Sketch: $\kappa_e - 1 \leq PoA \leq c(\kappa_e^2 + \log n)$



Optimal Nash-routing  
(Players use shortest paths)  
 $C = 1$



Worst Case Nash-routing  
(Players use longest paths)  
 $C = n - 1 = \kappa_e - 1$

If network is not a cycle, use the largest cycle in the network.

# Proof Sketch: $\kappa_e - 1 \leq PoA \leq c(\kappa_e^2 + \log n)$

**Combinatorial Lemma** If  $G$  is 2-connected, then  $\kappa_e(G) \geq \sqrt{2\ell} - \frac{3}{2}$ .

**2-connected Networks:**

$\ell = O(\kappa_e^2)$ , so

$PoA \leq 2(\ell + \log n) \implies PoA = O(\kappa_e^2 + \log^2 n)$ .

**General Networks:**

Step 1: Decompose  $G$ : tree of 2-connected and acyclic components.

Step 2: Many players satisfied in some 2-connected component;

Step 3: Extend  $PoA \leq 2(\ell + \log n)$  to **Partial Nash-routing**.

Step 4: Use 2-connected and Partial Nash-routing results.

# Wrap Up

- Studied general congestion games with **max. social/player costs**.
- Appropriate metrics when delays are important in congested networks.
- $PoS = 1$  and selfish dynamics are good.
- **Path Length Bound on  $PoA$** :  $PoA \leq 2(\ell + \log n)$ .
- **Topological bounds on  $PoA$** :  $\kappa_e - 1 \leq PoA \leq c(\kappa_e^2 + \log^2 n)$ .
- **Conjecture[Lower bound is tight]**:  $PoA \leq \kappa_e$ .
- Non-congested networks:  $SC = C + D$ ;  $pc_i = C_i + |p_i|?$

## Thank You!

<http://www.cs.rpi.edu/~magdon>