

CSC 4356

# Interactive Computer Graphics

Lecture 6: Transformation in OpenGL

Rasterization: Line Drawing

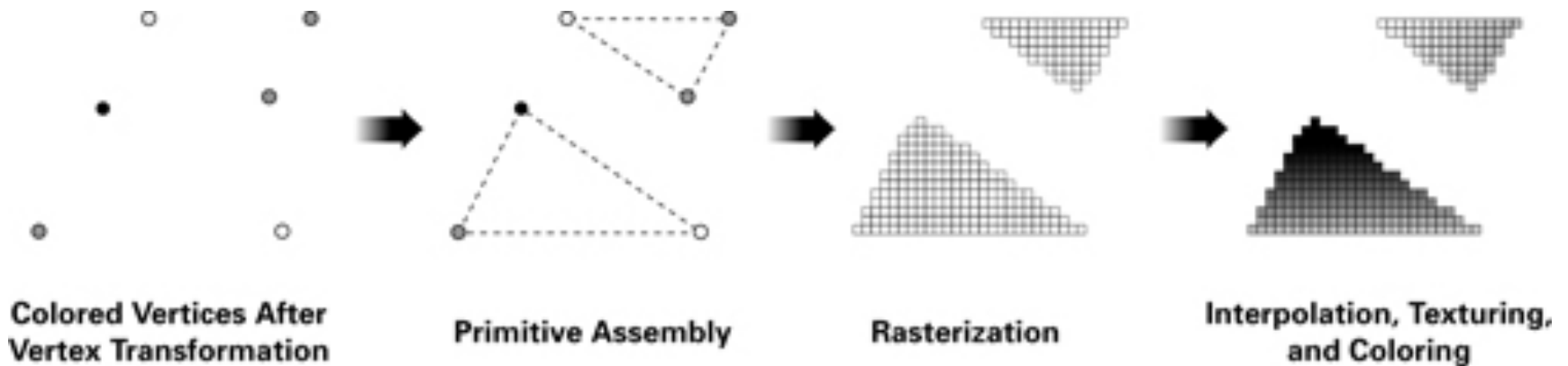
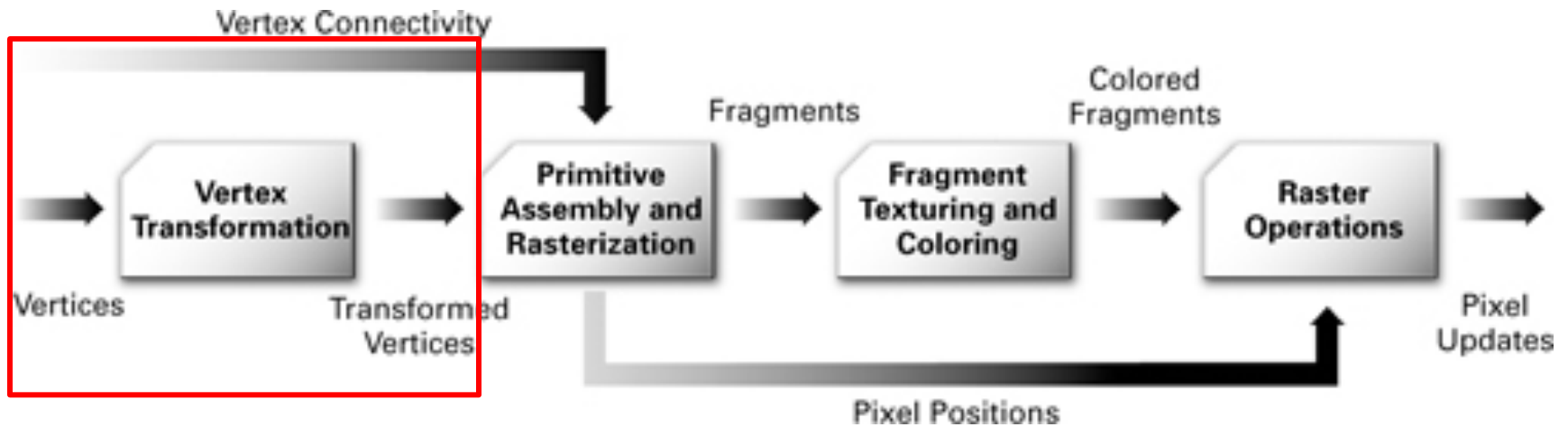
Jinwei Ye

<http://www.csc.lsu.edu/~jye/CSC4356/>

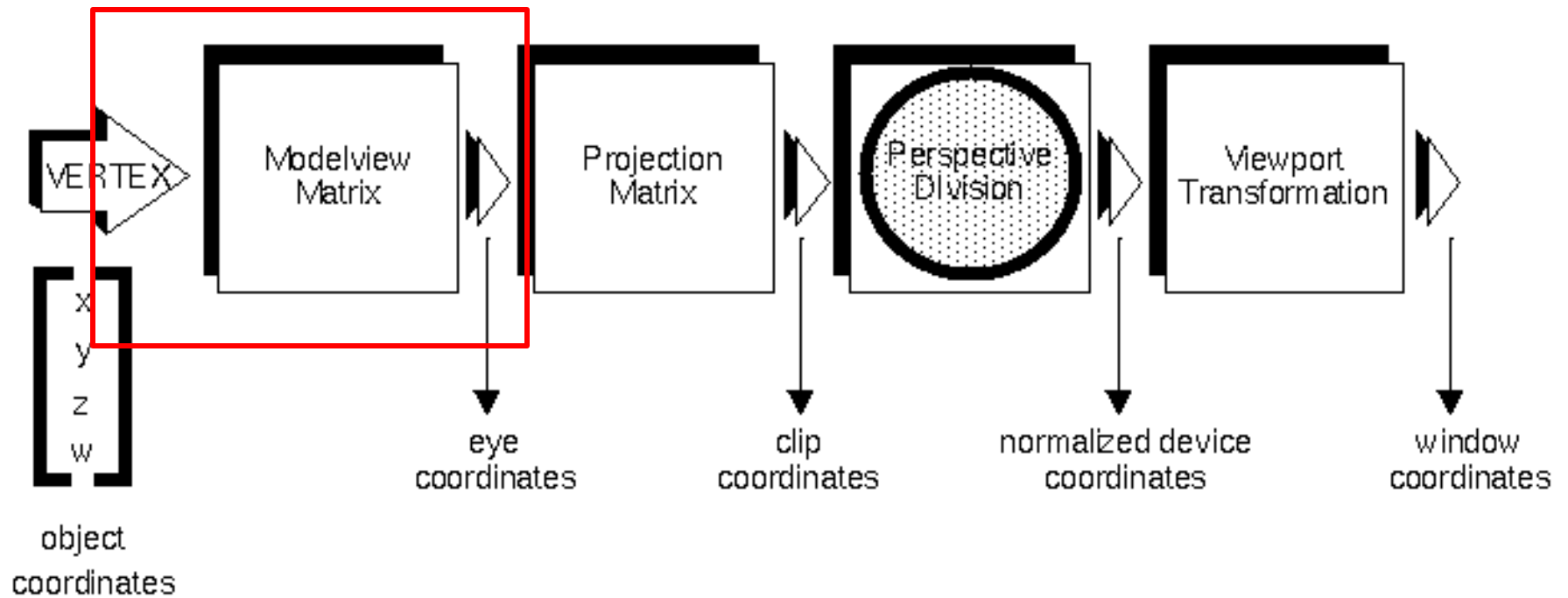
Tue & Thu: 10:30 - 11:50am

218 Tureaud Hall

# Graphics Rendering pipeline



# Vertex Transformation



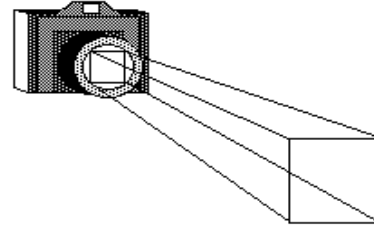
With a Camera

With a Computer

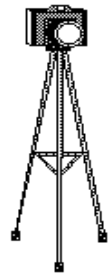
tripod



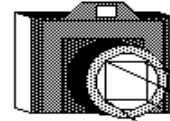
viewing



positioning the viewing volume  
in the world



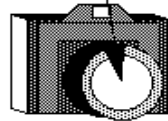
model



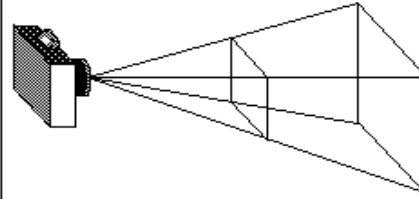
modeling

positioning the models  
in the world

lens

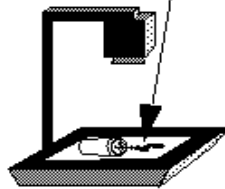


projection



determining shape of viewing volume

photograph



viewport



# ModelView Transformation

# ModelView Transformations

- Modeling Transformation
  - Position and orient the model in your scene
  - rotate, translate, scale
  - `glRotatef()`, `glTranslatef()`, `glScalef()`
- Viewing Transformation
  - Equivalent to position the camera
  - OpenGL always assume camera at (0,0,0)
  - Instead moving the camera, we have to move the scene
  - `gluLookAt()`

# OpenGL Matrix Stack

- OpenGL store *stacks* of 4 X 4 matrices
  - Stack: first in, last out
  - Initially, each stack contains one matrix, an identity matrix.
- `glMatrixMode()` specifies which matrix is the current matrix
  - `GL_MODELVIEW`, `GL_PROJECTION`, `GL_TEXTURE`, etc.
- Use `glGet(GL_MATRIX_MODE)` to inquire the current matrix stack

# Matrix Stack Operations

- OpenGL manages the matrix stack by push, pop, multiply matrices on top of the stack
  - glLoadMatrix()/glLoadIdentity()
  - glPushMatrix()
  - glPopMatrix()
  - glMultiMatrix()
  - glRotatef(), glTranslatef(), glScalef()
- *All vertices are multiplied by the top of stack*

# Functions

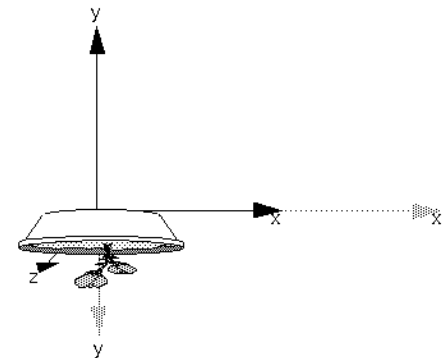
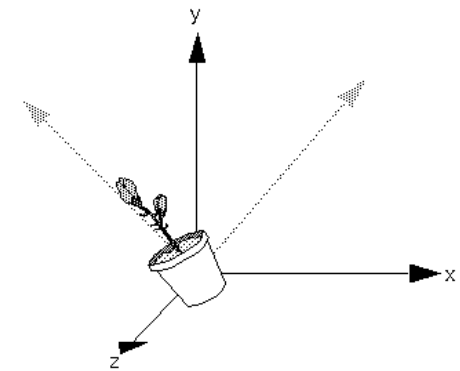
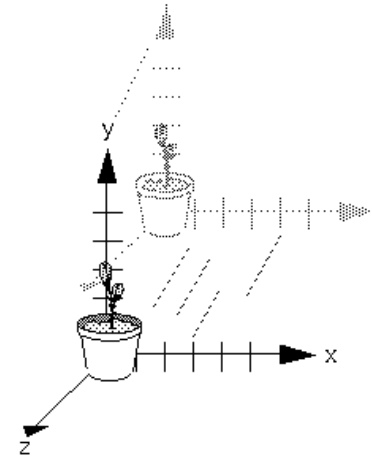
- `glLoadMatrix{fd}(m1,m2,...,m16)`
  - Set matrix M as the current matrix in stack
- `glLoadIdentity()`
  - Clear the current matrix as a 4 x 4 identity matrix
- `glMultMatrix{fd}(m1,m2,...,m16)`
  - Multiply matrix M onto the top of stack

$$\mathbf{M} = \begin{bmatrix} m_1 & m_5 & m_9 & m_{13} \\ m_2 & m_6 & m_{10} & m_{14} \\ m_3 & m_7 & m_{11} & m_{15} \\ m_4 & m_8 & m_{12} & m_{16} \end{bmatrix}$$



# Functions

- `glTranslate{fd}(x,y,z)`
  - Move the object by  $(x,y,z)$
- `glRotate{fd}(angle,x,y,z)`
  - Rotate the object by the angle about axis  $(x,y,z)$
  - Direction: counter-clockwise
- `glScale{fd}(sx,sy,sz)`
  - Scale the  $x, y, z$  coordinate of the object by  $s_x, s_y, s_z$
  - Reflection included



# Functions

- `glPushMatrix()`
  - pushes the current matrix stack down by one, duplicating the current matrix
  - the matrix on top of the stack is identical to the one below it
- `glPopMatrix()`
  - pops the current matrix stack
  - replacing the current matrix with the one below it on the stack
- Need to use in pair
- Similar to `save(Push)/load(Pop)`
- Useful when transforming multiple objects in different ways

# Example

```
glMatrixMode (GL_MODELVIEW) ;  
glLoadIdentity() ;           //load a 4x4 identity matrix  
glMultMatrixf (N) ;          //apply transformation N  
glMultMatrixf (M) ;          //apply transformation M  
glMultMatrixf (L) ;          //apply transformation L  
  
glBegin (GL_POINTS) ;  
glVertex3f (v) ;             //draw transformed vertex v  
glEnd() ;
```

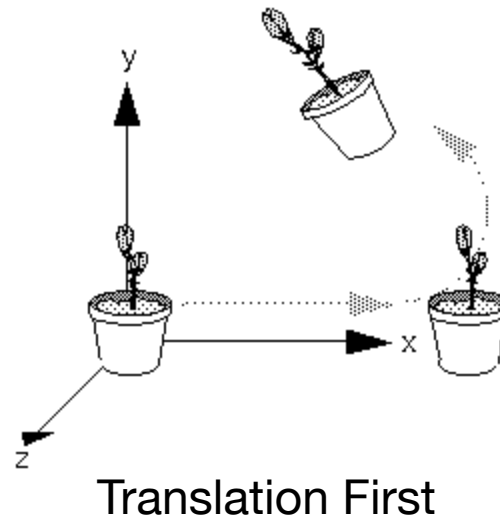
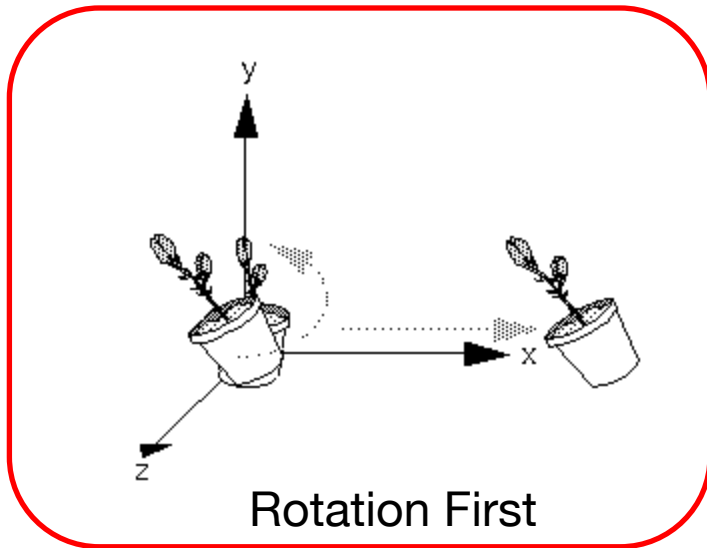
**First apply transformation L, then M, and finally N**

$$v' = NMLv$$

# Which Order?

```
glMatrixMode (GL_MODELVIEW) ;  
glLoadIdentity() ;  
glTranslatef (xt, yt, zt) ;  
glRotatef ( $\theta$ , x, y, z) ;
```

```
DrawObject ;
```



# Transform Multiple Objects

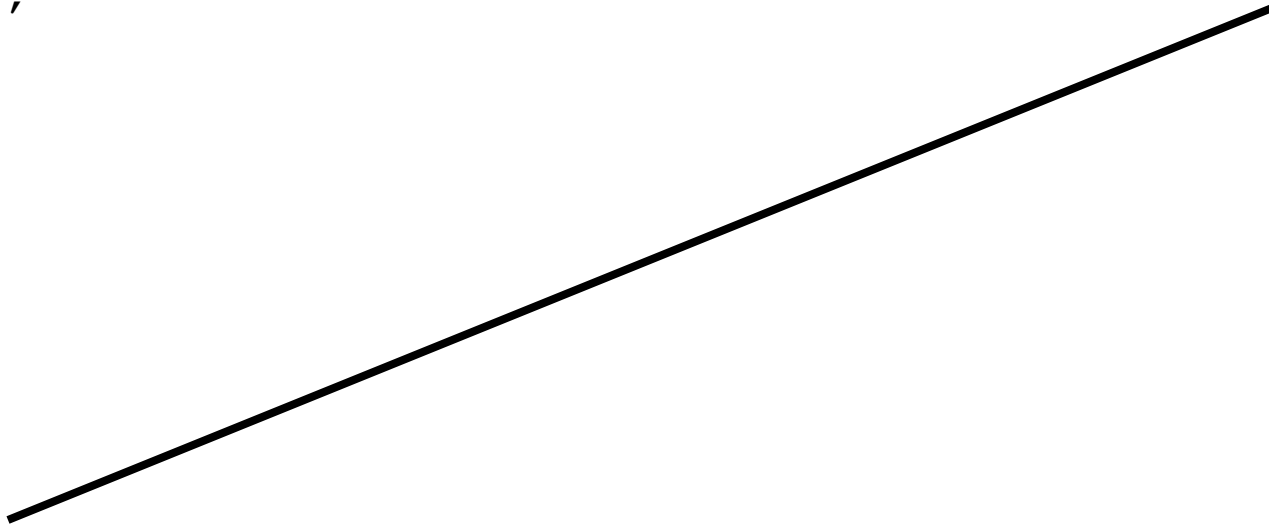
```
glPushMatrix();  
Transformations for object one;  
DrawObject(ONE);  
glPopMatrix();
```

```
glPushMatrix();  
Transformations for object two;  
DrawObject(TWO);  
glPopMatrix();
```

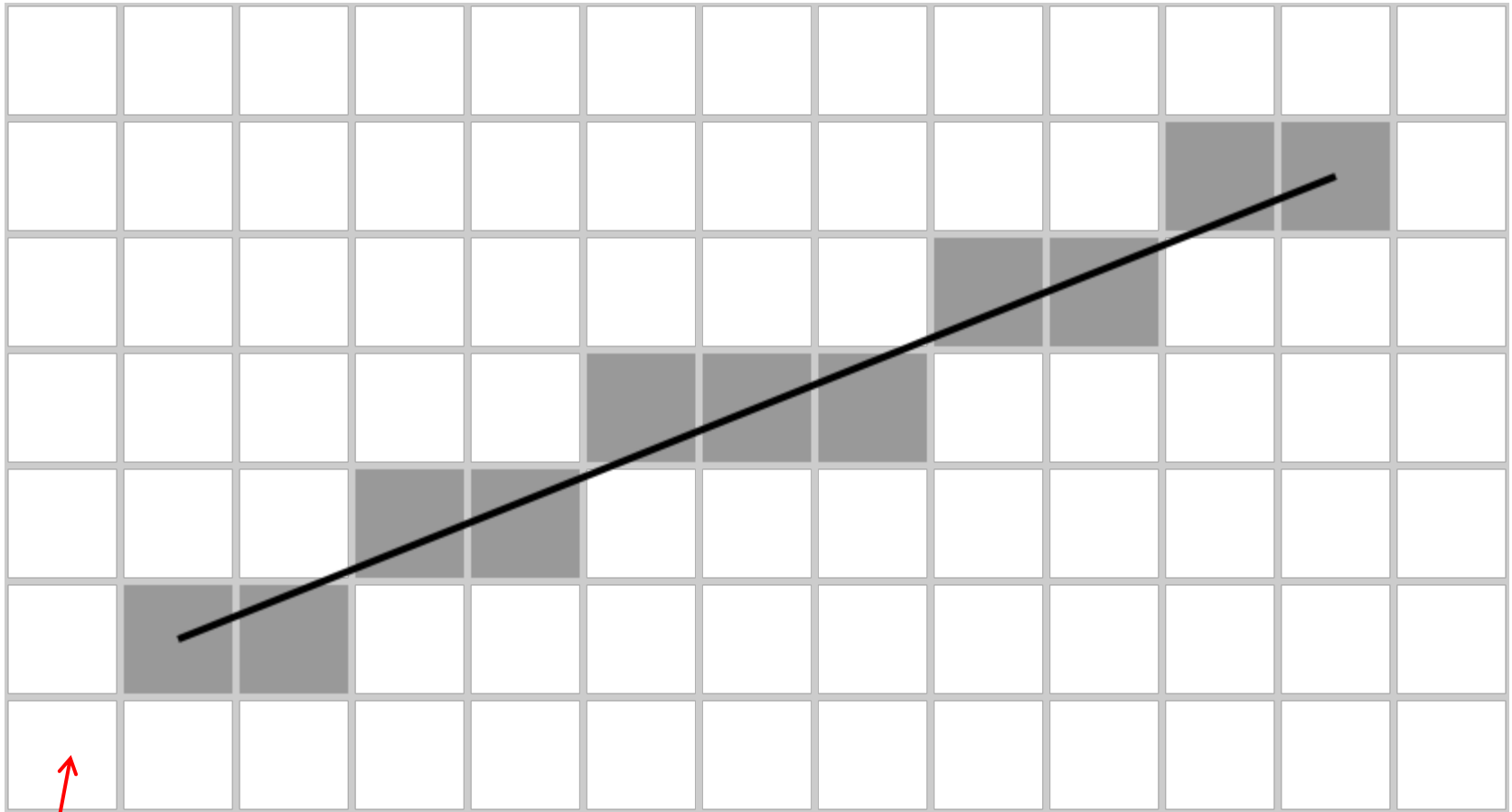
...

# How does OpenGL draw a line?

```
glBegin(GL_LINES);  
    glVertex3f (x1, y1, z1);  
    glVertex3f (x2, y2, z2);  
glEnd();
```



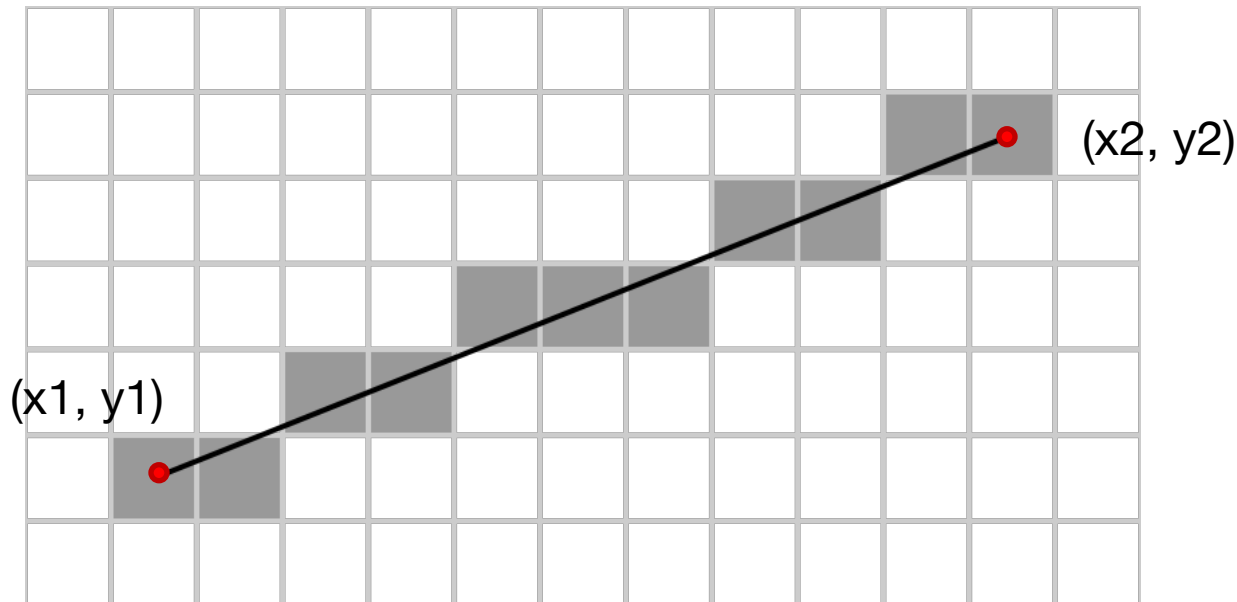
# Everything is rasterized!



Pixel

# Line Rasterization Problem

- Given:
  - Two endpoints: integers  $(x_1, y_1)$  &  $(x_2, y_2)$
- Identify:
  - Which pixels  $(x, y)$  to display for the line?



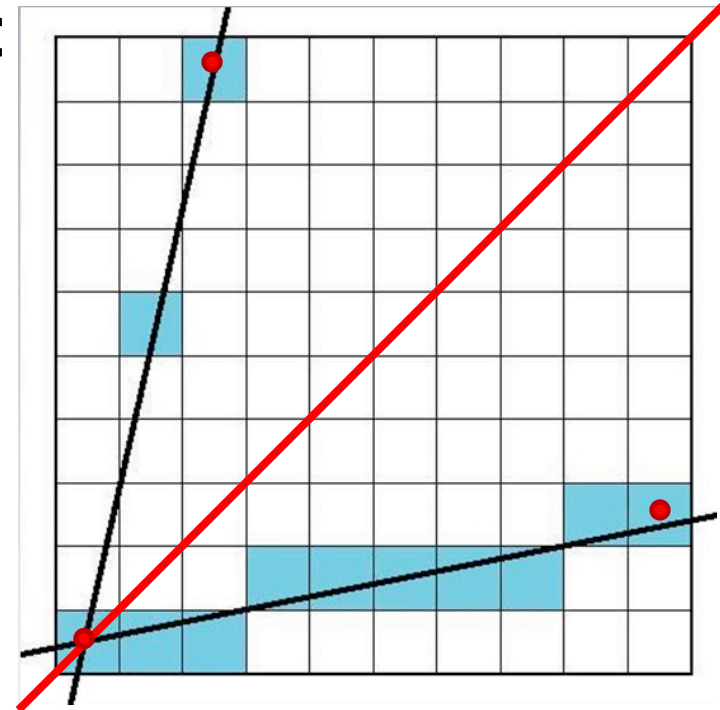


# Requirements

- Transform **continuous** primitive into **discrete** samples
- Uniform thickness & brightness
- Continuous appearance
- No gaps
- Accuracy
- Speed

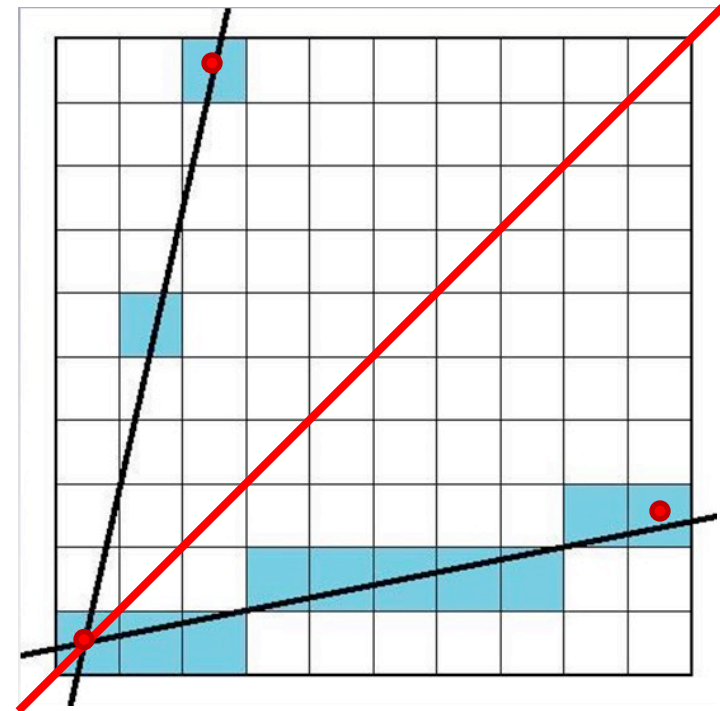
# DDA Line Drawing

- DDA stands for Digital Differential Analyzer, the name of a class of old machines used for plotting functions
- Slope-intercept form of a line:  
$$y = mx + b$$
  
slope:  $m = dy/dx$   
intercept:  $b$  is where the line intersects the  $y$ -axis



# DDA Line Drawing

- Basic idea: If we increment the x coordinate by one pixel at each step, the slope of the line tells us how much to increment y per step
  - i.e.,  $dx = 1$ ,  $dy = m$   
(because  $m = dy/dx$ )



# DDA Line Drawing

- This only works if  $m \leq 1$ 
  - otherwise there are gaps
- Solution: Reverse axes and step in  $y$  direction
  - Now  $dy = 1$ ,  $dx = 1/m < 1$

