Visualization of Irregular Data

Types of Volume Data

- Regular
 - Regular grids are orthographic and the nodes are equally spaced and lie at integer positions; connectivity information is implicit
- Rectilinear
 - Orthographic with non-constantly spaced nodes
- Curvilinear
 - Non-orthographic with non-constantly spaced grid nodes
- Unstructured
 - No logical organization and no implicit cell-adjacency information.









curvilinear

unstructured

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Different Rendering Approaches

- Resampling to a regular grid
 - Involve two steps:
 - Identify the cell in which a sampling point is actually located
 - Interpolate F inside a warped (nonregular) cell primitive based on the values of F at the cell's nodes.
 - Often results in large grids
 Large cells require substantial subsampling
- Direct rendering through projection
 - > All cells are projected onto the image plane in back-to-front or front-to-back order
 - Compute color and opacity from the data at grid nodes
 - ➢ Use depth-sorted lists of the cell faces per pixel for correct color accumulation
- Raycasting of nonregular/unstructured data
 - Computational-space-based
 - Sweep-plane-based

Computational Space Based Raycasting

- Raycasting is applied in regular computational space
 - Avoids difficulties of computing ray/cell-face intersections and of performing interpolations
 - Speeds up the visualization process
- Computational space:
 - An abstract representation of the logical organization of nonregularly structured physical grid
 - Mapping the warped grid to a regular grid
 - Applicable to rectlinear and curvilinear grids
 - Size, quality and topology information of the original data is preserved.



Coordinates Transformation

• Relationship between physical coordinates and computational coordinates

$$x_i = J_{ij} \bullet \xi_j$$

with the Jacobian matrix

$$J_{ij} = \frac{\partial x_i}{\partial \xi_j}$$



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Casting Rays

• Assign rays (vectors) at all physical nodes

Direction is determined by the viewpoint and the projection type

• Use isoparametric formulation to transform the vectors to computational space using

$$r_{Cj} = J_{ij}^{-1} \bullet r_{Pi} \quad \text{with } \mathbf{J}_{ij} = \frac{\partial \mathbf{x}_i}{\partial \xi_j} = \frac{1}{2} \cdot \left(\frac{\mathbf{x}_i(n) - \mathbf{x}_i(n-1)}{\xi_j(n) - \xi_j(n-1)} + \frac{\mathbf{x}_i(n+1) - \mathbf{x}_i(n)}{\xi_j(n+1) - \xi_j(n)} \right)$$
$$r_{Cj} = \frac{1}{2} \left[x_i(n+1) - x_i(n-1) \right]^{-1} \bullet r_{Pi}$$





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Bent Rays

• Tangential curves in the vector field $\mathbf{r_c}$ are the rays $\mathbf{R_c}$ through the computational space

$$\frac{d\xi_j}{dt} = r_{Cj}(\xi_i)$$

with *t* as the integrational parameter along a streamline



Example: 2D Case



Sweep-Plane Based Raycasting

- A hybrid-type approach
- Handles unstructured irregular grids
 - Including disconnected and nonconvex grids
 - Using adjacency information to determine ordering
- Sweeping 3D-space reduces the raycasting problem to a 2D cell sorting problem
 - Sweep-plane is orthogonal to the viewing plane (the xy-plane) and parallel to scanlines (i.e., parallel to the xz plane)
 - Raycasting within each slice of the sweep plane by a sweep line method.



Sweep Data Structure and Algorithm

- Sort the vertices of mesh S by their y-coordinates and put them into an event priority queue, an array A
- Use the active tetrahedra list (ATL) to maintain a list of the tetrahedra currently intersected by the sweep plane
- While A is not empty, do:
 - > Pop the event queue until hit is vertex
 - ➢ Update ATL
 - Render current scanline
- The algorithm terminates once the last scanline is processed.

References

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