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| Computer Architecture |  | \\ (CSC-3501) \\ Lecture 3 \\ (22 Jan 2008)}

Seung-Jong Park (Jay)
http://www.csc.Isu.edu/~sjpark

## Announcement

- Today, $1^{\text {st }}$ homework will be uploaded at our class website
$\square$ Due date is the beginning of next lecture
$\square$ Late homework grade will be dropped $20 \%$ per date late


## Floating Point

- The signed magnitude, one's complement, and two's complement representation that we have just presented deal with integer values only.
- Without modification, these formats are not useful in scientific or business applications that deal with real number values.
- Floating-point representation solves this problem.
- If we are clever programmers, we can perform floating-point calculations using any integer format.
- This is called floating-point emulation, because floating point values aren't stored as such, we just create programs that make it seem as if floatingpoint values are being used.
- Most of today's computers are equipped with specialized hardware that performs floating-point arithmetic with no special programming required.


## Floating Point Representation

- Computers use a form of scientific notation for floating-point representation
- Numbers written in scientific notation have three components:

- Computer representation of a floatingpoint number consists of three fixedsize fields:
$\square$ The IEEE-754 single precision floating point standard uses an 8-bit exponent and a 23-bit significand.
$\square$ The IEEE-754 double precision standard uses an 11-bit exponent and a 52-bit significand.



## How to Convert to Base-2 Floating Point

- Example:
$\square$ Express $32_{10}$ in the simplified 14-bit floatingpoint model.
$\square$ Convert $32_{10}$ to Base 2
- $100000_{2}=1.0 \times 2^{5}$
$\square$ Normalize (leftmost bit of the significand must be 1)
- $1.0 \times 2^{5}=0.1 \times 2^{6} \longrightarrow 00110$

For illustrative purposes, we will use a 14-bit model with a 5-bit exponent and an 8-bit significand.

## Why Normalization?

- The illustrations shown at the right are all equivalent representations for 32 using our simplified model.
- Not only do these synonymous representations waste space, but they can also cause confusion.

- Rule: leftmost bit of the significand must be 1.


## How to Represent Negative Exponent $2^{-2}$ ?

- Biased exponent
$\square$ Exponent larger than biased is positive integer exponent
$\square$ Exponent smaller than biased is negative integer exponent
$\square$ Example 1: express $32_{10}$ in the revised 14 -bit floating-point model.
- We know that $32=1.0 \times 2^{5}=0.1 \times 2^{6}$.
- To use our excess 16 biased exponent, we add 16 to 6 , giving $22_{10}\left(=10110_{2}\right)$.

- Negative Exponent
$\square$ Example 2 : express $0.0625_{10}$ in the revised 14-bit floating-point model.
- We know that 0.0625 is $2^{-4}$.
- So in (binary) scientific notation $0.0625=1.0 \times 2^{-4}=0.1 \times 2^{-3}$.
- To use our excess 16 biased exponent, we add 16 to -3 , giving $13_{10}\left(=01101_{2}\right)$.



## Another Example of Floating Point

- Example:
$\square$ Express $-26.625_{10}$ in the revised 14-bit floating-point model.
- We find $26.625_{10}=11010.101_{2}$.
$\square$ Integral part $26=11010_{2}$
- Fractional part $0.625=0.101_{2}$
- $0.625 \times 2=0.25 \xrightarrow{1}$ (generate 1 and continue with the rest)
- $0.25 \times 2=0.50$ (generate 0 and continue)
- $0.5 \times 2=$ (1. $0 \quad 1$ (generate 1 and nothing remains)
- Normalizing, we have: $26.625_{10}=11010.101_{2}=0.11010102 \times 2^{5}$.
- To use our excess 16 biased exponent, we add 16 to 5 , giving $21_{10}\left(-10101_{2}\right.$ ). We also need a 1 in the sign bit.



## IEEE-754 Floating Point Standard

- Both the 14 -bit model that we have presented and the IEEE-754 floating point standard allow two representations for zero.
$\square$ Zero is indicated by all zeros in the exponent and the significand, but the sign bit can be either 0 or 1 .
- This is why programmers should avoid testing a floating-point value for equality to zero.
$\square$ Negative zero does not equal positive zero.

| Number | Sign | Exponent | Fraction |
| :--- | :--- | :--- | :--- |
| 0 | X | 00000000 | 00000000000000000000000 |
| $\infty$ | 0 | 11111111 | 00000000000000000000000 |
| $-\infty$ | 1 | 11111111 | 00000000000000000000000 |
| NaN | X | 11111111 | non-zero |

NaN is used for numbers that don't exist, such as $\sqrt{ }-1$ or $\log (-5)$.

## History of Character Codes

- The earliest computer coding systems used six bits.
$\square$ Binary-coded decimal (BCD) was one of these early codes. It was used by IBM mainframes in the 1950s and 1960s.
- In 1964, BCD was extended to an 8-bit code, Extended BinaryCoded Decimal Interchange Code (EBCDIC).
$\square$ EBCDIC was one of the first widely-used computer codes that supported upper and lowercase alphabetic characters, in addition to special characters, such as punctuation and control characters.
$\square$ EBCDIC and BCD are still in use by IBM mainframes today.
- Other computer manufacturers chose the 7-bit ASCII (American Standard Code for Information Interchange) as a replacement for 6bit codes.
$\square$ While BCD and EBCDIC were based upon punched card codes, ASCII was based upon telecommunications (Telex) codes.
$\square$ Until recently, ASCII was the dominant character code outside the IBM mainframe world.


## Character Codes (Cont)

- Many of today's systems embrace Unicode, a 16-bit system that can encode the characters of every language in the world.
$\square$ The Java programming language, and some operating systems now use Unicode as their default character code.
- The Unicode codespace is divided into six parts. The first part is for Western alphabet codes, including English, Greek, and Russian.

| Character <br> Types | Language | Number of <br> Characters | Hexadecimal <br> Values |
| :---: | :--- | :---: | :---: |
| Alphabets | Latin, Greek, <br> Cyrillic, etc. | 8192 | 0000 <br> to <br> 1FFF |
| Symbols | Dingbats. <br> Mathematical, <br> etc. | 4096 | 2000 <br> to <br> 2FFF |
| CJK | Chinese, <br> Japanese, <br> and Korean <br> phonetic <br> symbols and <br> punctuation. | 4096 | 3000 <br> to <br> 3FFF |
| Han | Unified Chinese, <br> Japanese, and <br> Korean | 40,960 | 4000 <br> to <br> DFFF |
|  | Han Expansion | 4096 | EOOO <br> to <br> EFFF |
| User <br> Defined | 4095 | FO00 <br> to <br> FFFE |  |

## Error Detection

- It is physically impossible for any data recording or transmission medium to be 100\% perfect 100\% of the time over its entire expected useful life.
$\square$ Thus, error detection and correction is critical to accurate data transmission, storage and retrieval.
- Error Detection
$\square$ Parity bit can check some simple bit error
- Sometimes high-order bit of ASCII coded to enable detection of errors
- Even parity - set bit to make number of 1's even A (01000001) with even parity is 01000001 C (01000011) with even parity is 11000011



## Cyclic redundancy checking (CRC)

- CRC utilizes the redundant bits at the end of the block
- It is more powerful method
- Method
$\square$ Original message $M(x) /$ Generator polynomial $G(x)$
$\square$ Quotient is discarded
$\square$ Remainder is attached to message in BCC (Block Check Character)

- Commonly used cyclic codes
$\square$ CRC-12 $\mathrm{G}(\mathrm{x})=\mathrm{x}_{12}+\mathrm{x}_{11}+\mathrm{x}_{3}+\mathrm{x}_{2}+\mathrm{x}+1$
$\square$ CRC-16 G $(x)=x_{16}+x_{15}+x_{2}+1$
$\square$ CRC-CCITT G $(x)=x_{16}+x_{12}+x_{5}+1$


## CRC Example at page 83

- Encode
$\square$ Original Message $=1001011$
- $M(x)=1 x^{6}+0 x^{5}+0 x^{4}+1 x^{3}+0 x^{2}+1 x^{1}+1 x^{0}=x^{6}+x^{3}+x^{1}+1$
- $G(x)=1 x^{3}+0 x^{2}+1 x^{1}+1 x^{0}=x^{3}+x^{1}+1$
$\square$ Shift $M(x)$ Make large number before division
- $M(x) X x^{3}=x^{9}+x^{6}+x^{4}+x^{3}=1001011000$
$\square M(x) X x^{3} / G(x)$
- $1001011000 / 1011$ = quotient is 1010 and remainder is 100
$\square$ Add remainder 100 to 1001011000
- $1001011000+100=1001011100$
- Decode
$\square$ Encoded message / G(x)
- 1001011100 / 1011 = quotient is 1010100 and remainder is Zero
$\square$ Zero remainder means no error
$\square$ Non-zero remainder means some errors


## Error Correction

- Hamming code can detect errors and correct them.
$\square$ Hamming codes are code words formed by adding redundant check bits, or parity bits, to a data word.
$\square$ The Hamming distance between two code words is the number of bits in which two code words differ.

```
This pair of bytes has a 1 0 0 0 1 0 0 1
Hamming distance of 3: 10110001
```

$\square$ The minimum Hamming distance for a code is the smallest Hamming distance between all pairs of words in the code.
$\square$ The minimum Hamming distance for a code, $\mathrm{D}(\mathrm{min})$, determines its error detecting and error correcting capability.
$\square$ Hamming codes can detect $D$ (min) - 1 errors and correct $\left\lfloor\frac{\mathrm{D} \text { (Min) }-1}{2}\right\rfloor$ errors

## Hamming Code

- Example
$\square$ Using our code words of length 12, number each bit position starting with 1 in the low-order bit.
$\square$ Each bit position corresponding to an even power of 2 will be occupied by a check bit.
$\square$ These check bits contain the parity of each bit position for which it participates in the sum.

$$
\begin{array}{llllllllllll}
\overline{12} & -11 & \overline{10} & \overline{9} & 8 & \overline{7} & \overline{6} & \overline{5} & 4 & \overline{3} & 2 & 1
\end{array}
$$

- Since $2\left(=2^{1}\right)$ contributes to the digits, $2,3,6,7,10$, and 11 .

Position 2 will contain the parity for bits $3,6,7,10$, and 11 .
$\square$ Bit 1checks the digits, $3,5,7,9$, and 11, so its value is 1 to make even parity.
$\square$ Bit 4 checks the digits, $5,6,7$, and 12 , so its value is 1 .
$\square$ Bit 8 checks the digits, $9,10,11$, and 12 , so its value is also 1 .

| 1 | 1 | 0 | 1 | 1 | 0 | 1 | 1 | 1 | 0 | 0 | 1 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 |

## Hamming Code Cont.

- Suppose an error occurs in bit 5, as shown above. Our parity bit values are:
$\square$ Bit 1 checks digits, 3, 5, 7, 9, and 11. Its value is 1, but should be zero.
$\square$ Bit 2 checks digits 2, 3, 6, 7, 10, and 11. The zero is correct.
$\square$ Bit 4 checks digits, 5, 6, 7, and 12. Its value is 1, but should be zero.
$\square$ Bit 8 checks digits, $9,10,11$, and 12. This bit is correct.

| 1 | 1 | 0 | 1 | 1 | 0 | 1 | 0 | 1 | 0 | 0 | 1 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 | 3 | 2 | 1 |  |

$\square$ We have erroneous bits in positions 1 and 4.
$\square$ With two parity bits that don't check, we know that the error is in the data, and not in a parity bit.
$\square$ Which data bits are in error? We find out by adding the bit positions of the erroneous bits.
$\square$ Simply, $1+4=5$. This tells us that the error is in bit 5 . If we change bit 5 to a 1 , all parity bits check and our data is restored.

